INTRODUCTION

Most analytical models of ulse-echo imaging derive an integration on phoseduct of propagating pulse and the reflectors or scatterers, over the location of pulse at some point in time (Maskii, 1983; Szabo, 2004; Prince and Links, 2006). Under a number of approximations samplifications about attenuation and diffraction, the integration can be reduced to a convision model (Macovski, 1983).

The problems of poor resolution and speckle can be underated direct result of this convolution. The spatial resolution is set by the full spatial exterior the propagating pulse in 3D inch is typically many multiples of a wavelength. However, in tissue, small scatterers at the cellular level and micro-structural level such as the arterioles and capillaries will have a dimensions

zeroes of the pulse transform z become the poles of the invertisher. Generally, for a casual, right-handed system to be stable the poles of the transform must lie within the unit circle and the egion of convergence

FIGURE 2. An asymmetric pulse formed by multiplying the Gaussian envelope with a geometric series is shown in (a). The zeroes of the Z-transform are retracted into the unit circle as shown in (b). This leads to a stable inverse filter.

Now all the zeroes of the transform lie withine unit circle, as seen in Figure 2b. Accordingly, the inverse filter will have poles within the unit circle and will have a bounded input/bounded output impulse response of limited duration.

In general, we have found that the formation of a stabilized pulse is not restricted to the use of prefunction; rather this isillustrative of envelopes that have a shariptial rise and a more gradual fall-off from the peak. We call these "asymmetric" envelopes or pulses, and these can be characterized by a number of different

analytic functions. As an example, the functions $x^2 e^{\frac{x^2}{2}^2}$ UnitStep x is selected as a stable function for the transverse beampattern. The prograined II (Jensen, 2004) was used tonsiate a focused beampattern. The approximate Fourier transform of x is used to set the apodization function. A 5 MHz transducer with 129 active elements is simulated with halfawelength spacing. The transverse hereattern at the focus (60 mm depth) is shown in Figure 3. There is a goodtombetween the beampattern and the design funption

DISCUSSION AND CONCLUSIONS

An inverse filter approach has been derived using

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